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Main Features

Reference
Product code
Product reference
Accessory module (control)

- : CFW500B10P0T5DB66
- : 14979250
- : CFW500
- : CFW500-IOS

Basic data

Power supply	: 500-600 V	
Input minimum-maximum voltage	: 425-660 V	
- Input	: 3	
- Output	: 3	
Supply voltage range	500-6	600 V
Overload cicle	Normal Overload (ND)	Heavy Overload (HD)
Rated current	00001	10A
Overload current for 60 sec	Not applicable	15,0 A
Overload current for 3 sec	Not applicable	20,0 A

Maximum applicable motor:

Voltage/Frequency	Power (HP/kW) [1]		
voltage/Frequency	Normal Overload (ND)	Heavy Overload (HD)	
525V / 50Hz	Not applicable	7,5 / 5,5	
575V / 60Hz	Not applicable	10 / 7,5	
Not applicable	Not applicable	Not applicable	
Not applicable	Not applicable	Not applicable	
Not applicable	Not applicable	Not applicable	
Not applicable	Not applicable	Not applicable	
Not applicable	Not applicable	Not applicable	
Not applicable	Not applicable	Not applicable	

Not applicab			Not applicable		
Accessory module (control)		: CFW500-IOS			
Dynamic braking [2]		: Standard with brak	: Standard with braking		
External electronic suply 24Vcc		: Not available			
Safety Stop		: Not available			
Internal RFI filter		: Without filter			
External RFI filter		: Not available			
Link Inductor		: No			
Memory card		: Not included in the	product		
USB port		: Only with plug-in			
Line frequency		: 50/60Hz			
Line frequency range (minir	num - maximum)	: 48-62 Hz			
Phase unbalance		: Less or equal to 3%	6 of input rated line voltage		
Transient voltage and overv	/oltage	: Category III	: Category III		
Single-phase input current	[3]	: Not applicable	: Not applicable		
Three-phase input current [3]	: 12,2 A	,		
Typical input power factor		: 0,75			
Displacement factor			: 0,98		
Rated efficiency		:≥97%			
Maximum connections (pov	tions (power up cycles - on/off) per hour : 10 (1 each 6 minutes)		es)		
DC power supply	DC power supply : Al		: Allow		
Standard switching frequency		: 5 kHz	: 5 kHz		
Selectable switching frequency		: 2,5 and 15 kHz	: 2,5 and 15 kHz		
Real-time clock		: Not available	: Not available		
Copy Function		: Yes, by MMF ou plu	: Yes, by MMF ou plug-in		
Dissipated power:					
Mounting type	Overload				
	ND		HD		
Surface	Not applic	able	230 W		
Flange	Not applic	able	Not applicable		

Source available to the user Output voltage

Maximum capacity

Control/performance data

Power supply Control method - induction motor Encoder interface Control output frequency [5] Frequency resolution

: 24 Vcc : 150 mA

: Switched-mode power supply nduction motor : V/f, VVW, Sensorless, Encoder and VVW PM : Only with plug-in : 0-500 Hz on : 0,015 Hz

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Control/performance data

- V/F Control - Speed regulation - Speed variation **VVW Control**
- Speed regulation - Speed variation
- Sensorless vector control - Speed regulation
- Speed variation
- Vector control with Encoder - Speed regulation
 - Speed variation

Analog Inputs

Quantity (standard) Levels Impedance for voltage input Impedance for current input Function Maximum allowed voltage

Digital inputs

Quantity (standard) Activation Maximum low level Minimum high level Input current . Maximum input current Function Maximum allowed voltage

Analog outputs

Quantity (standard) Levels RL for voltage output RL for current output Function

Digital outputs

Quantity (standard) Maximum voltage Maximum current Function

Communication

- Modbus-RTU (with accessory: Any plug-in module)
- Modbus/TCP (with accessory CFW500-CEMB-
- TCP)
- Profibus DP (with accessory: CFW500-CPDP)
 Profibus DPV1 (with accessory: CFW500-CPDP)
- Profinet (with accessory CFW500-CEPN-IO)
- CANopen (with accessory: CFW500-CCAN)
- DeviceNet (with accessory: CFW500-CCAN)
- EtherNet/IP (with accessory CFW500-CETH-IP)
- EtherCAT (Not available)
- BACnet (CFW500 G2 / CFW501 G2 / MW500 G2
- with accessory: Any plug-in module)

Available protection

- Output phase-phase overcurrente/Short
- Overcurrent/Short circuit phase-ground
- Under/Overvoltage in power - Heat sink overtemperature
- Motor overload
- IGBT's modules overload
- Fault/External alarm
- Programming error

Operation interface (HMI)

Avaliability HMI installation Number of HMI buttons Display Indication accuracy Speed resolution

: Included in the product : Fixed HMI : 9 : Numeric LCD : 5% of rated current : 0,1 Hz



: 1% of rated speed

- : 1:20
- : 1% of rated speed : 1:30
- : 0,5% of rated speed : 1:100
- : 0,1% of nominal speed : Up to 0 rpm

: 1 : 0-10V, 0-20mA and 4-20mA : 100 kΩ : 500 Ω

- : Programmable
- : 30 Vcc

:4

- : Active low and high : 5 V (low) e 15 V (high)
- : 9 V (low) e 20 V (high)
- : 4,5 mA
- : 5,5 mA
- : Programmable
- : 30 Vcc
- 1 : 0 to 10V, 0 to 20mA and 4 to 20mA : 10 kΩ
- · 500 O
- : Programmable
- : 1 NO/NC relay and 1 transistor
- : 240 Vca and 24 Vcc
- : 0.5 A and 150 mA
- : Programmable

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Operation interface (HMI) Standard HMI degree of protection HMI battery type HMI battery life expectancy Remote HMI type Remote HMI frame Remote HMI degree of protection	: IP66 : Not applicable : Not applicable : Accessory : Not applicable : IP54
Ambient conditions	
Enclosure	: IP66
Pollution degree	: 2 (EN50178 and UL508C)
Temperature around the inverter: of -10 °C / 14 °F to 4 reduction of 2 % per °C of 40 (104) to 50 °C (122 °F).	40 °C / 104 °F. For temperatures above the specified is necessary to apply current
Relative humidity: 5% to 95% without condensation.	
100 m above (0,3% for each 100 ft above) of 1000 m	ns. Of 1000 m (3281 ft) to 4000 m (13123 ft) reduce the current in 1% for each (3281 ft). Reduce the maximum voltage (240 V for models 200240 V, 480 V for /) in 1,1% for each 100 m above (0,33% for each 100 ft above) of 2000 m.
Sustainability policies	
RoHS	: Yes
Conformal Coating	: 3C2 (IEC 60721-3-3:2002)
Dimensions and weigth	

- Size	: B (IP66)
- Height	: 340 mm / 13.4 in
- Width	: 215 mm / 8.46 in
- Depth	: 252.9 mm / 9.96 in
- Weight	: 9.3 kg / 20.5 lb
Mechanical Installation	
Mounting position	: Surface
Fixing screw	: M5
Tightening torque	: 5.5 N.m / 4.06 lb.ft
Allows side-by-side assembly	: No
Minimum spacing around the inverter:	
- Ton	· 50 mm / 1 97 in

- Тор	: 50 mm / 1.97 in
- Bottom	: 60 mm / 2.36 in
- Front	: 50 mm / 1.97 in
- Between inverters (IP20)	: 40 mm / 1.57 in

Electrical connections

Cable of	aaudes	and	tightening	toraues:
oubic ;	guugee	unu	ugincerning	lorques.

	Recommended cable gauge	Recommended tightening torque
Power	2,5 mm² (14 AWG)	1 N.m / 0.74 lb.ft
Braking	1,5 mm² (16 AWG)	1 N.m / 0.74 lb.ft
Grounding	2,5 mm² (14 AWG)	0.5 N.m / 0.37 lb.ft
Control	0,5 to 1,5 mm ² (20 to 14 AWG)	0,5 N.m / 0.37 lb.ft

SoftPLC	: Yes, incorporated
Maximum breaking current	: 9,0 A
Minimum resistance for the brake resistor	: 110 Ω
Recommended aR fuse [6]	: FNH00-25K-A
Recommended circuit breaker [6]	: Contact WEG
Disconnect switch	: Without disconnect switch
Motor coupling box	: Not applicable

Standards

Otaniaanas		
Safety Electromagnetic Compati	product standard including specific test methods. - EN 55011 - Limits and methods of measurement of racharacteristics of industrial, scientific and medical (ISM) equipment.	al and energy. tallations. t of machines. Part ccordance with that ble for the installation of uipment. systems - Part 2: Itage adjustable systems - Part 3: EMC dio disturbance
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Standards	
	 CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipment Electromagnetic disturbance characteristics - Limits and methods of measurement. EN 61000-4-2 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Electrostatic discharge immunity test. EN 61000-4-3 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 3: Radiated, radio-frequency, electromagnetic field immunity test.
	 EN 61000-4-4 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 4: Electrical fast transient/burst immunity test.
	 EN 61000-4-5 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 5: Surge immunity test. EN 61000-4-6 - Electromagnetic compatibility (EMC)- Part 4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances, induced by radio-frequency fields.
Mechanical Construction	- EN 60529, UL 50 and IEC 60721-3-3

Certifications

UL, CE, RCM, CS/IRAM, EAC, UKCA and RoHS CHINA

Notes

1) Motor power is orientative, valid for standard WEG Motors of IV poles. The correct sizing must be done according to the nominal current of the motor used, which must be less than or equal to the rated output current of the inverter;

2) Braking resistor is not included;

3) Considering minimum line impedance of 1%;

4) For more information, refer to the user manual of CFW500;

5) All images are merely illustrative.

6) For operation with switching frequency above nominal, apply derating to the output current (refer to the user manual).