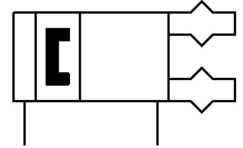
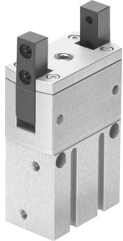


Radial gripper HGRT-16-A

Part number: 563904

FESTO



Data sheet

Feature	Value
Size	16
Max. interchangeability	≤ 0.2 mm
Max. gripper jaw angular play ax, ay	≤ 0.1 deg
Max. opening angle	180 deg
Rotational symmetry	≤ 0.2 mm
Pneumatic gripper repetition accuracy	≤ 0.02 mm
Type code	HGRT
Number of gripper jaws	2
Mounting position	Any
Mode of operation	Double-acting
Gripper function	Radial
Design	Positively driven motion sequence
Position sensing	For proximity sensor For inductive proximity sensors
Symbol	00991894
Operating pressure	3 bar ... 8 bar
Max. operating frequency of pneumatic gripper	≤ 3 Hz
Min. opening time at 6 bar	246 ms
Min. closing time at 6 bar	293 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	1 - Low corrosion stress
Ambient temperature	5 °C ... 60 °C
Total gripping torque at 6 bar, opening	188 Ncm
Total gripping torque at 6 bar, closing	158 Ncm
Mass moment of inertia	0.191 kgcm ²
Maximum force on gripper jaw Fz, static	50 N
Maximum torque on gripper jaw, My static	3.9 Nm
Maximum torque on gripper jaw, Mz static	0.3 Nm
Relubrication interval for guidance elements	10 MioCyc
Product weight	130 g
Type of mounting	With internal thread and centering sleeve
Pneumatic connection	M3
Note on materials	Free of copper and PTFE RoHS-compliant

Feature	Value
Housing material	Aluminum Smooth anodized
Gripper jaw material	Steel Hardened