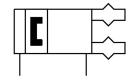
Parallel gripper HGPP-32-A Part number: 525664







Data sheet

Feature	Value
Size	32
Stroke per gripper jaw	12.5 mm
Max. interchangeability	0.1 mm
Pneumatic gripper repetition accuracy	≤0.02 mm
Type code	HGPP
Number of gripper jaws	2
Mode of operation	Double-acting
Gripper function	Parallel
Design	Gear rack/pinion
Position sensing	For Hall sensor For inductive proximity sensors
Symbol	00991894
Total gripping force at 6 bar, opening	830 N
Total gripping force at 6 bar, closing	830 N
Operating pressure	2 bar 8 bar
Max. operating frequency of pneumatic gripper	4 Hz
Min. opening time at 6 bar	76 ms
Min. closing time at 6 bar	110 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	2 - Moderate corrosion stress
Ambient temperature	5 ℃ 60 ℃
Gripping force per gripper jaw at 6 bar, opening	415 N
Gripping force per gripper jaw at 6 bar, closing	415 N
Maximum force on gripper jaw Fz, static	720 N
Maximum torque on gripper jaw, Mx static	30 Nm
Maximum torque on gripper jaw, My static	30 Nm
Maximum torque on gripper jaw, Mz static	30 Nm
Max. mass per external gripper finger	300 g
Product weight	1408 g
Type of mounting	With internal thread
Pneumatic connection	G1/8
Note on materials	Free of copper and PTFE
Cover cap material	POM
Housing material	Wrought aluminum alloy Hard-anodized

Feature	Value
Gripper jaw material	Wrought aluminum alloy Nickel-plated