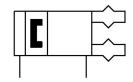
Parallel gripper HGPP-12-A Part number: 187867







Data sheet

Feature	Value
Size	12
Stroke per gripper jaw	2.5 mm
Max. interchangeability	0.1 mm
Pneumatic gripper repetition accuracy	≤0.02 mm
Type code	HGPP
Number of gripper jaws	2
Mode of operation	Double-acting
Gripper function	Parallel
Design	Gear rack/pinion
Position sensing	For Hall sensor For inductive proximity sensors
Symbol	00991894
Total gripping force at 6 bar, opening	116 N
Total gripping force at 6 bar, closing	116 N
Operating pressure	2 bar 8 bar
Max. operating frequency of pneumatic gripper	4 Hz
Min. opening time at 6 bar	27 ms
Min. closing time at 6 bar	40 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	2 - Moderate corrosion stress
Ambient temperature	5 °C 60 °C
Gripping force per gripper jaw at 6 bar, opening	58 N
Gripping force per gripper jaw at 6 bar, closing	58 N
Maximum force on gripper jaw Fz, static	70 N
Maximum torque on gripper jaw, Mx static	3 Nm
Maximum torque on gripper jaw, My static	3 Nm
Maximum torque on gripper jaw, Mz static	3 Nm
Max. mass per external gripper finger	100 g
Product weight	172 g
Type of mounting	With internal thread
Pneumatic connection	M3
Note on materials	Free of copper and PTFE
Cover cap material	POM
Housing material	Wrought aluminum alloy Hard-anodized

Feature	Value
Gripper jaw material	Wrought aluminum alloy Nickel-plated