

Parallel gripper DHPC-10-A-NO-Z

Part number: 8116762

FESTO



Data sheet

Feature	Value
Size	10
Operating pressure	50.75 psi ... 116 psi
Operating pressure	0.35 MPa ... 0.8 MPa
Stroke per gripper jaw	2 mm
Max. interchangeability	0.2 mm
Max. gripper jaw angular play ax, ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotational symmetry	≤0.2 mm
Pneumatic gripper repetition accuracy	≤0.02 mm
Type code	DHPC
Number of gripper jaws	2
Mounting position	Any
Mode of operation	Single-acting Open
Gripper function	Parallel
Design	Connection via mounting spigot Lever Standard mounting type for gripper fingers Positively driven motion sequence
Guide	Ball guide
Position sensing	For proximity sensor
Symbol	00997349
Total gripping force at 6 bar, closing	32.8 N
Operating pressure	3.5 bar ... 8 bar
Max. operating frequency of pneumatic gripper	3 Hz
Min. opening time at 6 bar	28 ms
Min. closing time at 6 bar	26 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	0 - No corrosion stress
Ambient temperature	-10 °C ... 60 °C
Gripping force per gripper jaw at 6 bar, closing	16.4 N
Mass moment of inertia	0.049 kgcm ²
Maximum force on gripper jaw Fz, static	29 N
Maximum torque on gripper jaw, Mx static	0.13 Nm
Maximum torque on gripper jaw, My static	0.27 Nm
Maximum torque on gripper jaw, Mz static	0.13 Nm

Feature	Value
Max. mass per external gripper finger	120 g
Product weight	66 g
Type of mounting	Optionally: Direct mounting via through-hole Direct fastening via thread On mounting frame With through-hole and dowel pin With internal thread and dowel pin
Pneumatic connection	M5
Note on materials	Free of copper and PTFE RoHS-compliant
Housing material	Aluminum, anodized
Gripper jaw material	High-alloy stainless steel