## Parallel gripper DHPC-L-10-A-NO-S Part number: 8116777

**FESTO** 



| Feature  | Value  |
|--|--|
| Size   | 10   |
| Operating pressure                               | 50.75 psi 116 psi  |
| Operating pressure                               | 0.35 MPa 0.8 MPa   |
| Stroke per gripper jaw                           | 4 mm   |
| Max. interchangeability                          | 0.2 mm   |
| Max. gripper jaw angular play ax, ay             | 0 deg  |
| Max. gripper jaw backlash Sz                     | 0 mm   |
| Rotational symmetry                              | ≤0.2 mm  |
| Pneumatic gripper repetition accuracy            | ≤0.02 mm   |
| Type code  | DHPC   |
| Number of gripper jaws                           | 2  |
| Mounting position                                | Any  |
| Mode of operation                                | Single-acting<br>Open  |
| Gripper function                                 | Parallel   |
| Design   | Connection direction at side<br>Lever<br>Standard mounting type for gripper fingers<br>Positively driven motion sequence |
| Guide  | Ball guide   |
| Position sensing                                 | For proximity sensor   |
| Symbol   | 00997349   |
| Total gripping force at 6 bar, closing           | 32.8 N   |
| Operating pressure                               | 3.5 bar 8 bar  |
| Max. operating frequency of pneumatic gripper    | 3 Hz   |
| Min. opening time at 6 bar                       | 22 ms  |
| Min. closing time at 6 bar                       | 12 ms  |
| Operating medium                                 | Compressed air as per ISO 8573-1:2010 [7:4:4]  |
| Information on operating and pilot media         | Operation with oil lubrication possible (required for further use)   |
| Corrosion resistance class (CRC)                 | 0 - No corrosion stress  |
| Ambient temperature                              | -10 °C 60 °C   |
| Gripping force per gripper jaw at 6 bar, closing | 16.4 N   |
| Mass moment of inertia                           | 0.062 kgcm <sup>2</sup>  |
| Maximum force on gripper jaw Fz, static          | 29 N   |
| Maximum torque on gripper jaw, Mx static         | 0.13 Nm  |
| Maximum torque on gripper jaw, My static         | 0.27 Nm  |
| Maximum torque on gripper jaw, Mz static         | 0.13 Nm  |

| Feature                               | Value   |
|---------------------------------------|---|
| Max. mass per external gripper finger | 120 g   |
| Product weight                        | 66 g  |
| Type of mounting                      | Optionally: Direct mounting via through-hole Direct fastening via thread With through-hole and dowel pin With internal thread and dowel pin |
| Pneumatic connection                  | M3  |
| Note on materials                     | Free of copper and PTFE<br>RoHS-compliant   |
| Housing material                      | Aluminum, anodized  |
| Gripper jaw material                  | High-alloy stainless steel  |